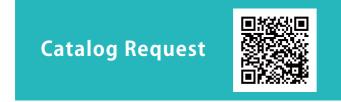
# FA · Industrial Robot Related Products Complete Catalog

Kosmek Products for Automation and Setup Improvement in Every Process

# FA • Industrial Robot

# **Related Products**

Products : Robotic Hand Changers, Pneumatic Robotic Hands, Clamps, High-Accuracy Locating / Setup Change Products, Auto Couplers and Supports

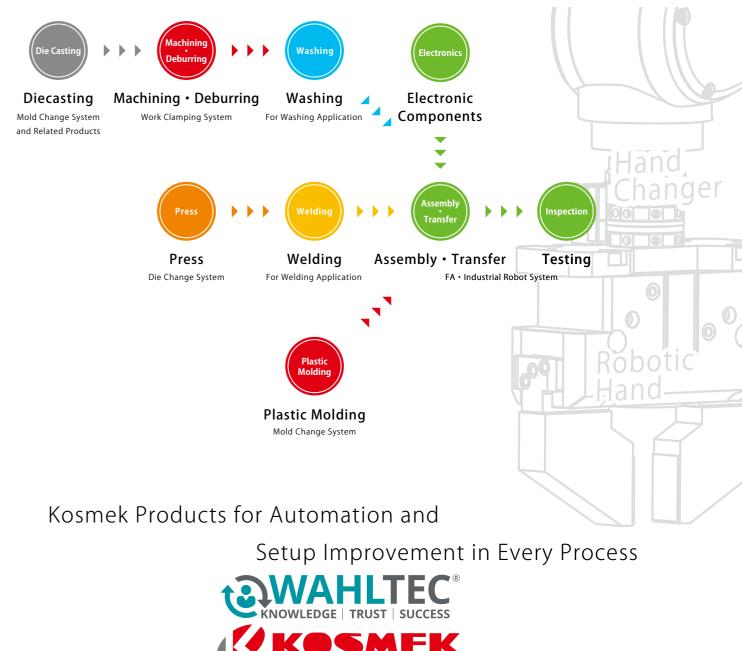




# Product Line-up - FA Series -

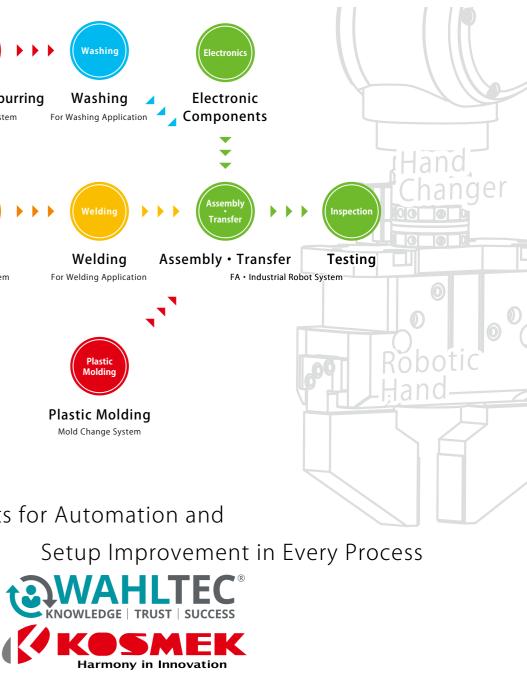
- March 2022 -

Introducing Kosmek FA · Industrial Robot Related Products & Products by Application











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For Further Information on Unlisted Specifications and Sizes, Please call us. Specifications in this Leaflet are Subject to Change without Notice.

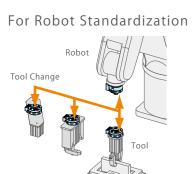


http://www.kosmek.com/

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# Introducing Kosmek New Products & Products by Application

# **Tool Changing**





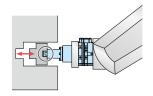
**Robotic Hand Changer** Accessories for SWR model SWR / SWRZ / SWRA



For Pallet Transfer



For Workpiece Transfer



Compact Parallel Robotic

Hand Gripper with Dust Cover

model WPB

▶ P.11

For Workpiece Clamping

NFW

and Transfer

FA Pneumatic Hole Clamp model WKH ▶ P.10

NEW

Pneumatic

Swing Clamp

model WHC

▶ P.7



NEW Hole Gripper model WKK ▶ P.9



High-Power Pneumatic

Hole Clamp

model SWE

▶ P.10

NEW

Pallet Gripper model WVA ▶ P.25

NEW

Manual Robotic

Hand Changer

model SXR

▶ P.3

Internal Diameter Chucking Series



NFW

**Robotic Hand Changer** 

model SWL

Refer to Kosmek Website.

(Large Model)





model WKA

▶ P.29

Locating Pin Clamp model SWP





External Chucking Series



Pneumatic Robotic Hands model WPA/WPE/WPF/WPH/WPJ/WPP/WPO/WPS/WPW ▶ P.11



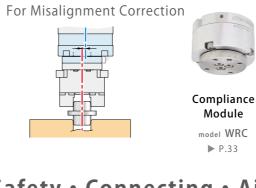
Pneumatic **Centering Vise** model FWD ▶ P.27



High-Power **Pneumatic Clamp** model WHE/WCE



# Correcting \_\_\_\_\_



# Safety • Connecting • Air Pressure Maintaining -





Air Safety Valve model BWS

Auto Coupler model JVA0100/JVB0100 ▶ P.17

model JWC/JWD ▶ P.20

# Welding —

▶ P.19

NEW



Locating Pin Clamp

When Released When Locked

model SWP ▶ P.15

# Setup Changing





For Locating and Clamping of Conveyor Transfer Pallet





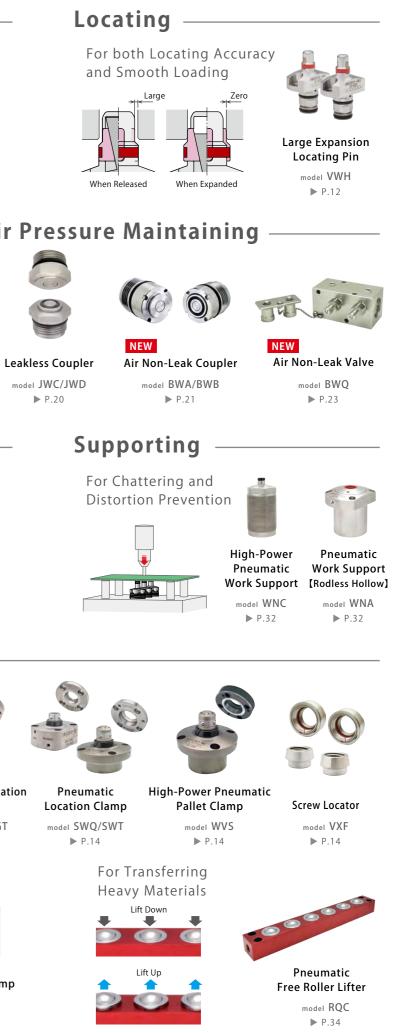
Lifting Hole Clamp

Lifting Locating + Clamping

model SWJ ▶ P.31







For FA • Industrial Robots



**Product Description Video** The description video of Manual Roboti Hand Changer is available on our website





# NEW

# Manual Robotic Hand Changer

model **SXR** 

Enables manual quick change of the end of arm tooling, it is best suitable to collaborative robots (cobots). Line-up of Payload : 0.5~1 kg Model, 3~5kg Model, and Additional 7~10 kg Model.





SXR Robot Installation Samples



# **Best Suitable to Collaborative Robot !** Manual **Quick Change**





Applicable Robot : CRX

Applicable Robot : COBOTTA





Applicable Robot : ASSISTA

Applicable Robot : duAro



Applicable Robot : TM ROBOT



Push in the pusher to attach/detach a tool.



Attach the tool.



Completed. \* It becomes the locked state with built-in spring when releasing the pushers.





# Additional Line-up

# model **SXR0070** 7 ~ 10kg Payload



Applicable Robot : HC10DTP



Applicable Robot : UR





Robotic Hand Changer **Robotic Hand Changer** 

# model **SWR**

Robotic Hand Changer enables standardization of robots. Even more flexible to use with the new options: Ethernet Electrode, Ground Electrode and Servo Electrode.

HIGH Accuracy	Repeatability 0.003mm
<b>HIGH</b> Durability	Durability Test more than 2 Million Cycles
QUICK Delivery	With Completed Product Inventory Immediately Delivered

LARGE Selection of Lineup

Payload from **0.5kg** up to **360kg** 

# A Variety of Electrode and Air Joint Options

- For connecting signal lines For noncontact connecting
- For using under mist
- For connecting AC power
- For adding extra air ports

• For using in a washing device



# NEW Ethernet Electrode model SWR-L

Applicable to 100BASE-TX with M12 D-code 4-pole connector

New product to be released in Spring 2022. Check our website for further information.



# NEW Servo Electrode model SWR-F

Various signals such as motor power, encoder control and torque, and shield cable for noise reduction can be connected together with one electrode. This option is available for SWR0250 and larger sizes.

# NEW Ground Electrode model SWR-T

Ground Electrode is best suitable to arc welding robot. Its rated capacity is 500A (activity ratio 50%). This option is available for SWR0500 and larger sizes.



# New Accessory for Quick Connect of Robot and Hand Changer

NEW

Adapter Plate

model SWRZ

Designing or making an adapter plate is not required. Additional lineup: SWRZ-MF4 enables quick installation of the adapter plate to a robot flange with mounting pattern 4 which is adapted to many collaborative robots. Applicable to ISO Mounting Pattern.

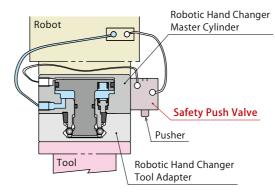


# New Accessory for Prevention of a Tool Fall





# Prevent a Tool Fall caused by Operational Error

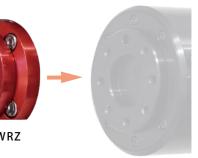


Locked State

During transfer, it will not be released even when the valve is switched.



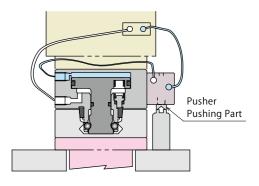






Safety Push Valve Fall Prevention Valve model **SWRA** 

Prevents a tool fall caused by operational error of a valve during robot teaching. Enables to limit SWR to release only at a designated position (stocker).



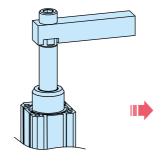
Release Enabled State Release operation is possible only at the tool stocker.

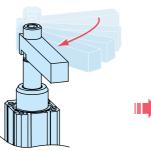
For FA • Industrial Robots





Action Description

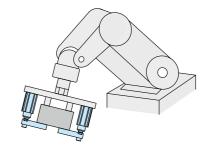




Before Swing (Released State)

The lever descends as it swings.

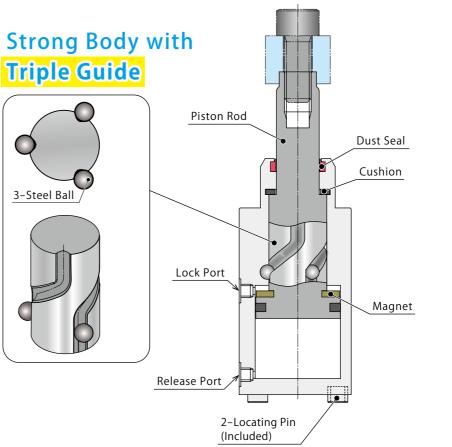
• Application Examples



For Clamping a Workpiece during Assembly, Machining and Testing

As a Robotic Hand

Cross Section



NEW Pneumatic Swing Clamp model WHC High-durability, high-speed and high-accuracy compact pneumatic

swing clamp. This clamp is coolant resistant, and can be used in various applications with the use of auto switch.

 $\sim$ 

# High Rigidity, Long Operational Life and High Accuracy with Powerful Swing Mechanism

High Speed  $\cdot$  High Rigidity  $\cdot \pm 0.5^{\circ}$  Swing Angle Position Repeatability

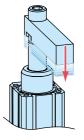


# One of the World's Smallest Compact Body \*According to our research.

# High Accuracy • Long Operational Life

Strong swing mechanism with **3 steel ball** tracking. Allows for high-speed and long operational life. (Conducted in-house operation test 2 million times.) For creating high-lifespan, environmentally friendly facilities. Swing Complete Position Repeatability : ±0.5° Swing Angle Accuracy :  $90\pm3^{\circ}$ 

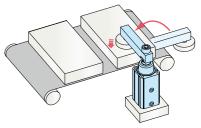




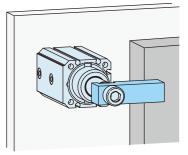
After swing completion, it descends vertically.



Action Completed (Clamped State)



For Clamping a Workpiece on a Device



# Wall mounting is also available.

% Please make sure to check "Notes for Lever Design" on the product catalog.

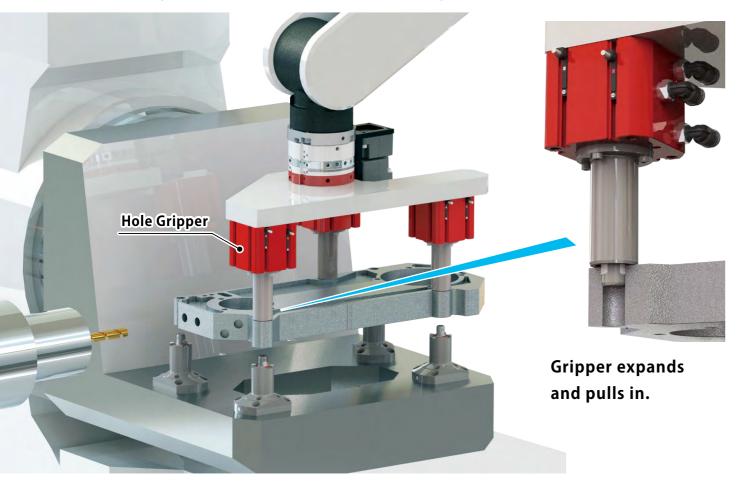


# NEW Hole Gripper

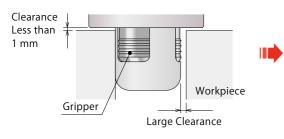
# model **WKK**

Transfers workpieces with I.D. gripping. Air blow function prevents cutting chips and coolant, allowing for transferring workpieces to and from various machining and die casting processes. Action confirmation is available by using an auto switch.

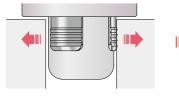
For transferring workpieces to and from various machining processes.



## Action Description



< Released State >



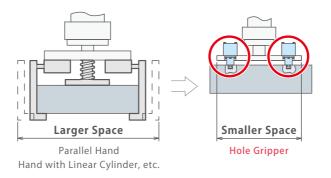


< Clamping State > The gripper expands to hold the workpiece hole.

< Clamping Completed > Pulls and clamps in the workpiece hole.

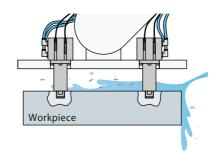
Light Weight • Smaller Footprint

WKK makes a robotic hand compact so that the transfer hands can be lighter and more compact.



• Wide Range of Seating Surface Heights

The available seating height options allows auto switches and air piping to be protected from coolant and cutting fluid by adjusting the seating height accordingly.



# **Robotic Hand I.D. Chucking Series**

A Wide Variety of Kosmek's I.D. Chucking Series. Gripping a workpiece hole enables more compact and lighter robotic hands. 5 faces are accessible with no tooling interference. Able to integrate processes.

**FA Pneumatic** Hole Clamp

Clamps a workpiece by holding its hole.

Applicable Workpiece Hole Diameter :  $\phi 6 \sim \phi 14$  in 0.5mm increments Locating Repeatability :  $30 \,\mu$  m



# **High-Power** Pneumatic Hole Clamp

Available for use inside the machine. Clamps a workpiece by holding its hole.

Applicable Workpiece Hole Diameter :  $\phi$  6 ~  $\phi$  13 in 0.5mm increments Locating Repeatability : None



model SWE

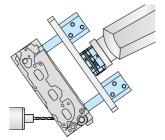
model WKH

9



# • Using Transfer Hand as Fixture

5 faces of a workpiece are accessible with no tooling interference. A robot can hold a workpiece and continue to the next processes such as deburring, washing, etc.



• Air Blow Function Ensures Longevity **Even in Machining Environments** 

By air purging from the inside, it prevents coolant from entering inside the hole gripper even with a little air flow.



# Locating Pin Clamp

Clamps and locates a hole of a thin workpiece from above.

Applicable Workpiece Hole Diameter :  $\phi 8 \sim \phi 20 (11 \text{ sizes})$ Locating Repeatability : 50  $\mu$  m





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# Pneumatic Robotic Hands

A variety of robotic hands are newly added to the lineup.



**Compact Parallel Robotic** Hand Gripper with Dust Cover

# model WPB

Robotic hand with a cover to prevent from contamination. The dust cover is available in 3 different materials (Polychloroprene, Silicone Rubber and Fluor Rubber).

Compact

Open

New

**Angular Gripper** 

6 Close : 17 ~ 216 N

: 39 ~ 158 N

Model WPA

Model WPJ



**Available in 3 Different Materials** Polychloroprene | Silicone Rubber | Fluor Rubber

New

5 Close

Parallel Gripper

:28~302 N

Model WPF

: 84 ~ 1589 N

: 93 ~ 1746 N

## **High-Power Parallel Gripper**

**2** Close : 94~133 N Holding Force: 287~ 400 N





Model WPS Compact









**Parallel Hand** with Auto-Grip Changer

Setup change by exchanging grippers (levers) to handle a wider variety of workpieces.



Model WPW

## New **Parallel Gripper** Wide Angular Gripper **4** Close : 29 ~ 133 N 6 Close

**External Chucking Series** 



Model WPE Three-Jaw Chuck

Close :187~3619 N 7 : 211 ~ 3707 N Oper



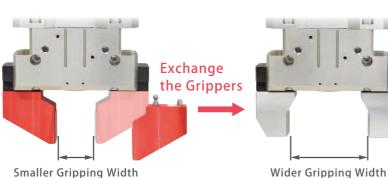
Model WPF



Two-Jaw Chuck

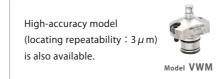
8 Close

Open







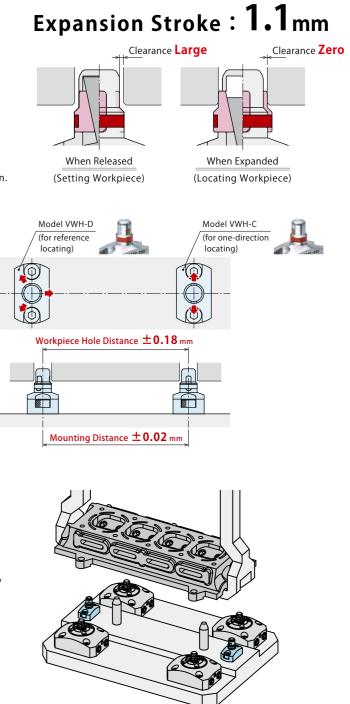


# **Expansion Locating Pin** enables High-Accuracy Locating.

Enables both smooth loading and high-accuracy locating. KOSMEK expansion locating pin absorbs variations in machining reference holes and reference hole distance. This enables high-accuracy locating and stable automation.

Ex.)

For a workpiece hole  $\phi 10^{+0.05}_{0}$  mm, Mounting Distance of Expansion Locating Pin: ±0.02mm Allowable Workpiece Hole Distance Variance: within  $\pm 0.18$  mm



# Suitable for Automation including Robot Transfer

The large expansion model has a large clearance when released, capable of automation such as robot transfer, etc.

11



# Large Expansion Locating Pin model **VWH**

With expansion stroke 1mm longer than conventional models,

the high accuracy expansion locating pin enables to automate

loading/unloading process with robot.

Workpiece Hole Diameter :  $\phi 9 \sim \phi 15$ , Locating Repeatability :  $10 \mu$  m



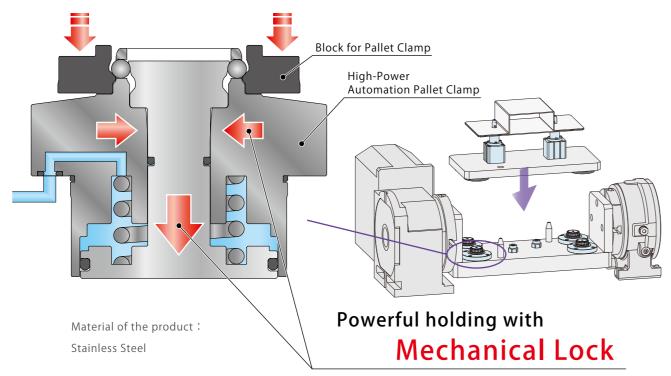
# High-Power Automation Pallet Clamp

model WVG Locates and clamps simultaneously.

Suitable for pallet transfer and fixture changeover with excellent loadability and safety function of powerful clamping force.

# Available in three body sizes.

# Clamping force is 4 kN / 6 kN / 10 kN



\* Clamping force varies depending on operating pressure. % This is a simplified drawing. Actual components are different.



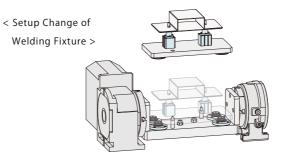
# Sensor Attachment

# Model WVGT

Detects the lock action and the release action of the clamp with the use of an auto switch (prepared by customer).

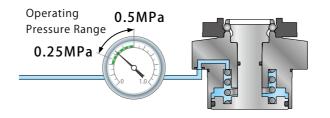
# Setup Improvement Enhances Productivity

High-Power Automation Pallet Clamp locates and clamps simultaneously. Fixture changeover becomes faster and easier, and equal clamping force and locating accuracy are ensured.



High Clamping Force (High Power)
 High Safety : Fall Prevention

Powerful clamping force with KOSMEK exclusive mechanical locking.



# Smooth Loading

The low profile of the clamping part reduces lifting amount when loading. Also, the short locating surface avoids jamming and enables smooth loading.

# 100% Stainless Steel

# Location Clamp

Enables simultaneous locating and clamping. Locating Repeatability : 3 µ m

Compact Air Location Clamp

# Air Location Clamp

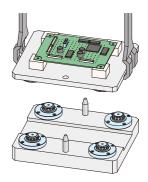
Suitable for setup change of compact pallets and light fixtures. Equipped with contamination High-power model to exert the force preventing function. that is equal to our hydraulic model.



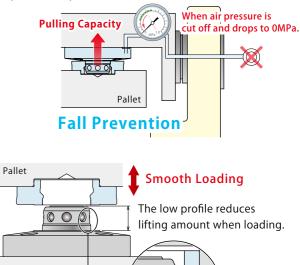




< Fixture Setup Change and Pallet Transfer of Automation Device >



Mechanical locking is built in some steel ball parts. This enables powerful holding even when air pressure is at OMPa. Powerful pulling capacity (holding force) prevents a pallet fall.



# High-Power Pneumatic Pallet Clamp

The short locating surface avoids jamming.



Screw Locator

**Bolt-Tightening** Manual Model







# NEW Locating Pin Clamp model **SWP**

Allows for high-accuracy locating and clamping of thin workpieces. Suitable for automation of clamping of spot welding workpieces. Equipped with air blow function to prevent contamination. Action confirmation with auto switch is possible.

# **Excellent for Automation, Prevents Machine Stops**

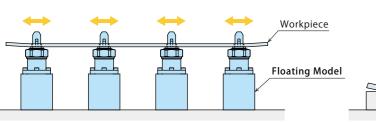
# C Additional Lineup : Floating Model

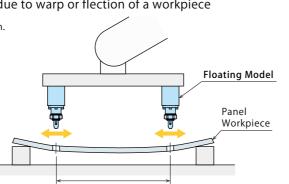
• In case of locating with locating model and requiring clamping force. The floating model enables additional clamping force without interfering the locating model.



# C Application Example of Floating Model

• In case there is a large variation in workpiece hole distance due to warp or flection of a workpiece Variation of workpiece hole distance can be absorbed by the floating function.



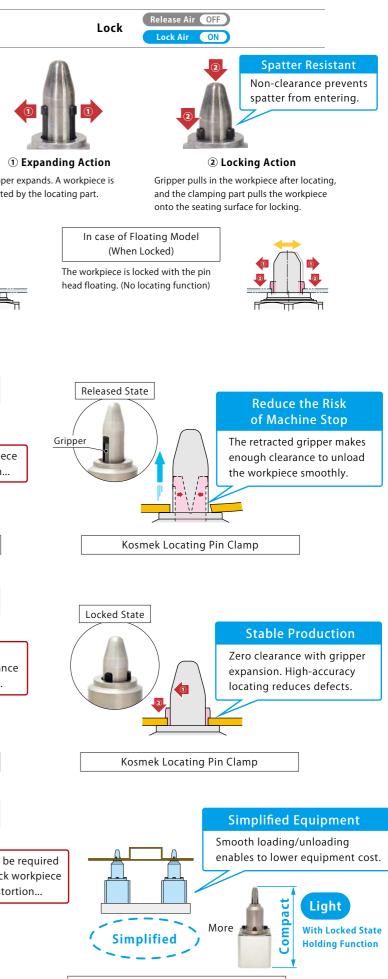


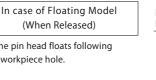
Variation of Workpiece Hole Distance due to Flection

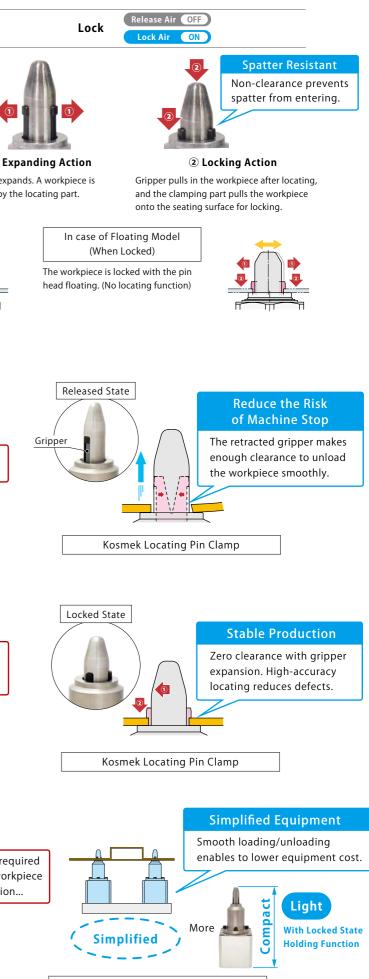
## Action Description

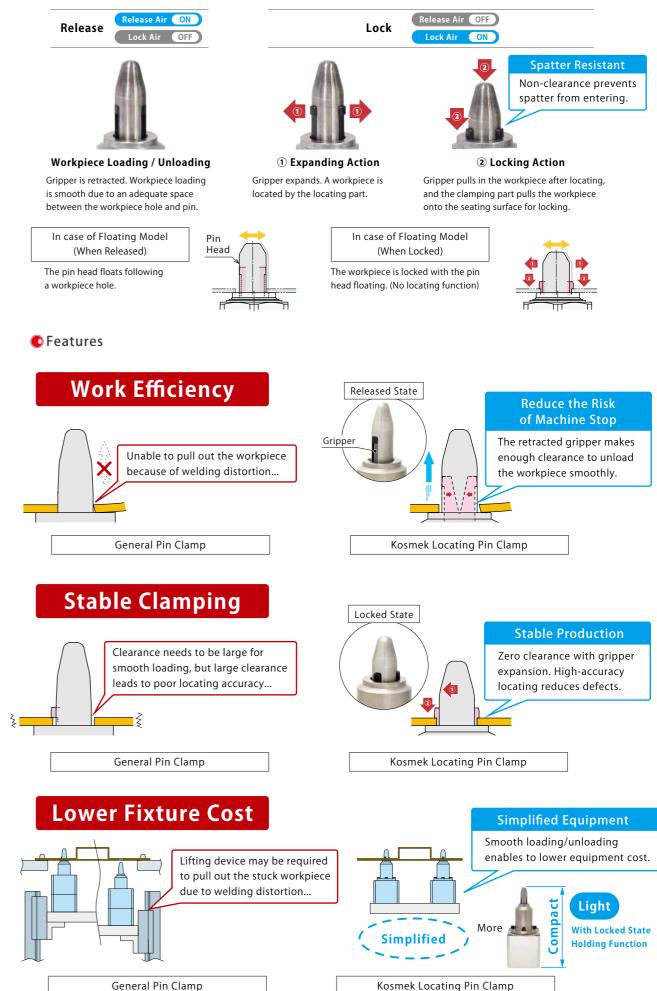














\* This is a full-scale photo.

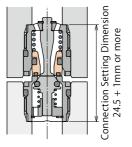
## C Action Description

JVA (Fixture Side)

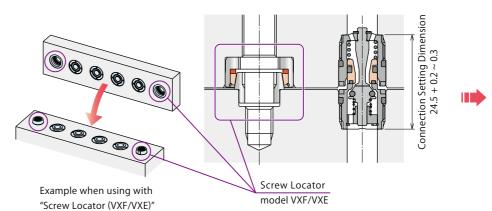
JVB (Pressure Source Side)

## Disconnected State

① When Not Using with Screw Locator Reaction force is not generated at the distance of 1mm or further than the connection setting dimensions (24.5mm). Reaction force is generated at the distance of 1mm or less than the connection setting dimensions (24.5mm).



② When Using with Screw Locator (VXF/VXE) The reaction force (spring force) is generated when setting up the pallet because the stroke of "Screw Locator" is 0.2 ~ 0.3mm. If using a light pallet, it may be lifted up when tightening.



## Specifications ※ Refer to the catalog for detailed specifications.

Model No.	Fixture	Fixture Side		JVA0100-H
WOULEI NO.	Pressur	Pressure Source Side		JVB0100-H
Max. Operating Pressure MPa			Pa	1.0
Min. Passage Area mm <sup>2</sup>			n2	8
Offset Distance (Tolerance) mm			m	±0.5
Angular Deviation (Tolerance) DEG.			G.	0.3
Operating Temperature °C			°C	0 ~ 120
Usable Fluid				Air or Vacuum
Reaction (	Operating	at 0.5 MPa		0.045
Force kN F	Pressure	at P MPa		$0.050 \times P + 0.02$
Waisht a		JVA0100		8
Weight g		JVB0100		6

## Notes for Usage (JVA0100/JVB0100)

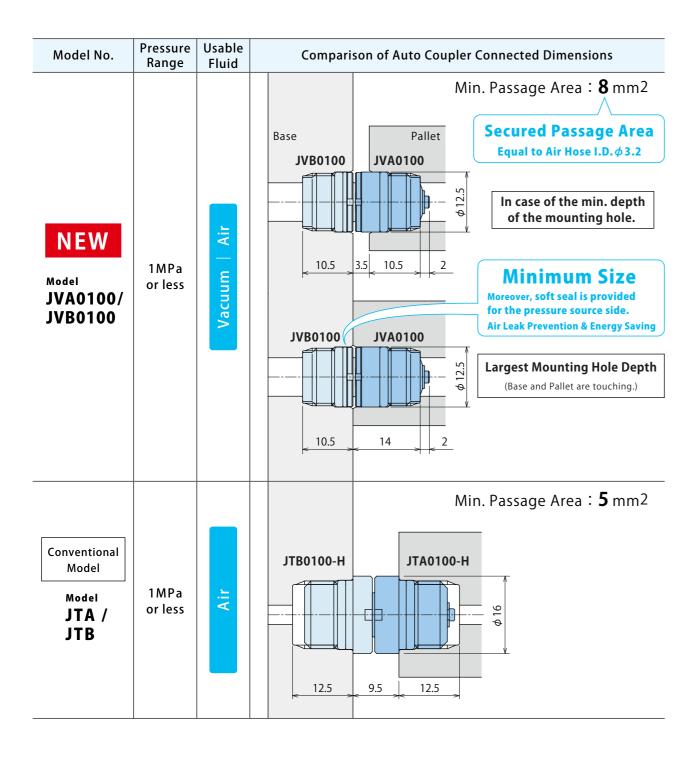
- 1. Do not connect or disconnect the auto coupler under pressure.
- 2. Do not connect the coupler when contaminants are adhered on each connecting surface.
- When there are cutting chips or coolant, install a cover, or remove all contaminants with air blow.
- 3. Exceeding allowable offset leads to damage on internal parts. It is recommended to install a guide pin, etc.
- 4. When pressing up to the connection limit, the force should be higher than the reaction force and lower than 0.25 kN.
- 5. A mounting jig is required to mount and remove the coupler. (Refer to the product catalog for further information.)

# NEW

Auto Coupler Compact · for Air / Vacuum

# model JVA0100/JVB0100

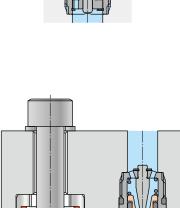
The new auto coupler is designed to be as compact as possible, and maximizes passage area. Applicable to air (positive pressure) and vacuum (negative pressure). The body is made of 100% stainless steel, and the seals are made of fluorine rubber. Connection stroke is 1mm, and it is easily used with Screw Locator (model VXE/VXF) for quick change.



17



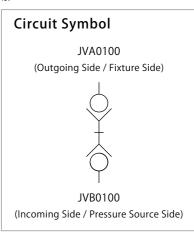
# In the Process of Connecting (Pallet Setting)



**Connected State** The reaction force is generated by

the built-in spring and the pressure

of provided fluid.



For FA • Industrial Robots

**Product Description Video** The description video of Air Safety Valve is available on our website



Bottom Surface

A Port





Weight

**M3 Thread Model** 

**M5 Thread Model** 

Rc1/8 Thread Model

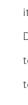
NEW

# NEW Air Safety Valve

model **BWS** 

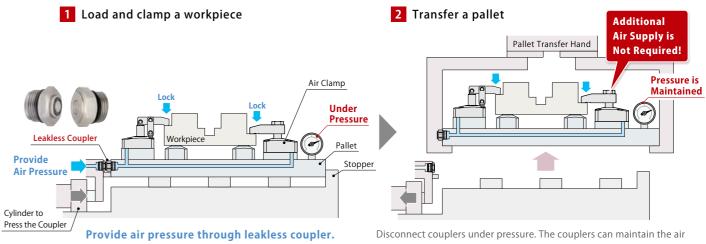
Ultra-Compact and -Light Air Pilot Check Valve for Safety. Prevents a workpiece fall during robot transfer. Rc1/8 thread model (BWS0101) is newly added to the lineup.

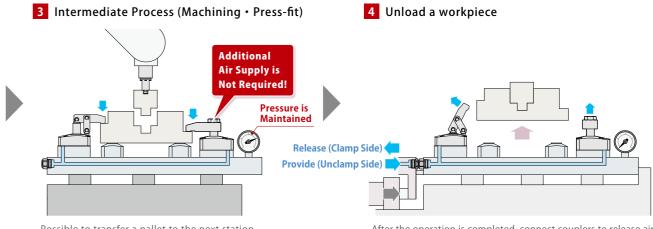




# Leakless Coupler To Solve Pallet Transfer Problems

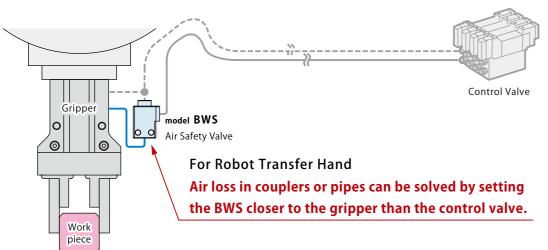
No need to provide air pressure when disconnected from air source. Leakless coupler can be disconnected while pressure is provided. Enables to remain air clamps in a locked state and transfer a workpiece to the next station.





Possible to transfer a pallet to the next station while clamp is in a locked state.

# • Application Example



grams

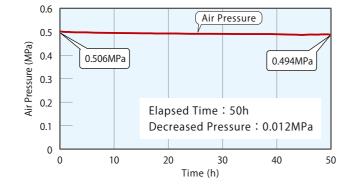
**arams** 

7 grams

# In the second second

Testing data of measuring elapsed time and pressure change when maintaining air pressure in A port. Sealing part is equipped with Soft Seal. It enables great pressure maintaining ability.

% Testing data of single product with stable surrounding temperature.



The description video of Leakless Couple is available on our website.

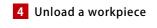




# Leakless Coupler model JWC/JWD

Leakless Coupler enables to maintain clamping force since it keeps the air pressure even if a coupler is disconnected. During pallet transfer, etc. between processes, it enables to remain a workpiece locked and transfer the workpiece to the next station.

pressure inside the circuit. Not necessary to provide the air pressure during pallet transfer. Without air tubing, flexible robot teaching is possible.



After the operation is completed, connect couplers to release air out. (Provide air pressure to unclamp port to unload a workpiece.)



# Air Non-Leak Coupler model BWA/BWB

By connecting and disconnecting under pressure, the BWA port

maintaining ability for more than 24 hours (under constant temperature).

(outgoing lock air) maintains air pressure after disconnected

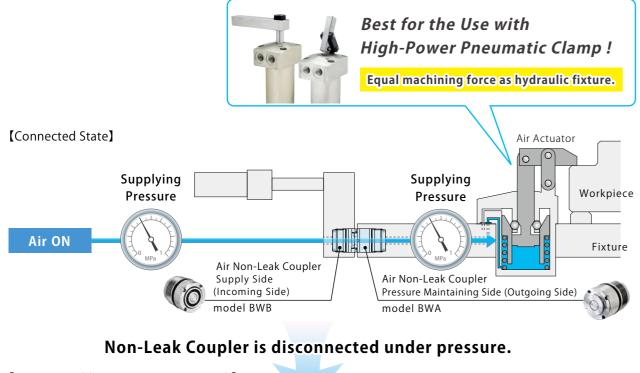
\* "Air Non-Leak" means that the BWA outgoing side has pressure

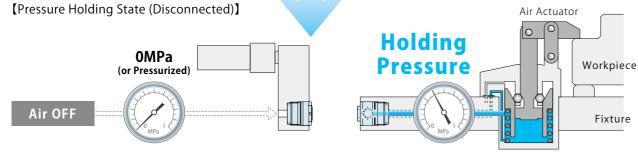
(Air Non-Leak\* Function).

World's First

Non-leak, which could only be achieved with hydraulics, is now possible with air.

# New release of the valve model BWA/BWB that achieves Air Non-Leak\*





# Setup Outside the Machine Improves Machine Up Time

Air non-leak function allows to disconnect a fixture from an air source and to prepare the fixture outside machine. This reduces machine down time and set up time.

# Reduce the Number of Circuits in the Machine

By holding the air pressure, the number of circuits for fixture inside the machine can be minimized.

# Outside Setup by Disconnecting Air of APC, Pallet Pooling, etc.

Because it is able to disconnect the fixture from the air source, it is suitable for pallet pooling. It allows to move pallets freely without concerns on handling of hoses, and it is also suitable for transferring with robot.

# • Energy-Saving with No Hydraulic Use

The non-leak function which could only be achieved with hydraulics is now possible with air.

Also, the same level of machining as a hydraulic fixture is possible by using with high-power pneumatic clamp.

# • Specifications \* Refer to the catalog for detailed specifications.

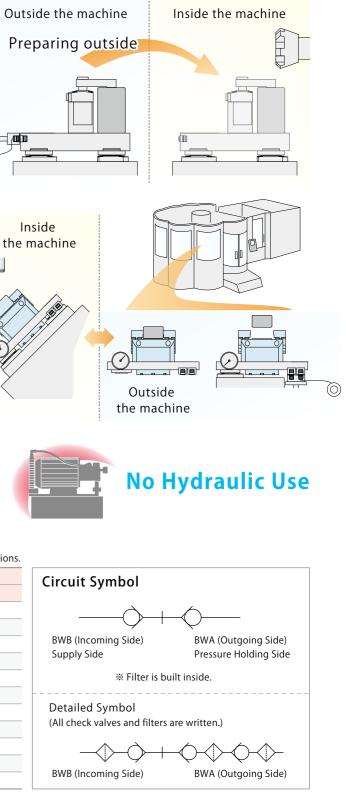
·				
Model No.		Pressure Holding Side		BWA0100
		Supply Side		BWB0100
Max. Opera	Max. Operating Pressure		MPa	1.0
Min. Passage Area		a	mm <sup>2</sup>	9.6
Offset Distance (Tolerance)		olerance)	mm	±0.5
Angular Deviation (Tolerance)		n (Tolerance)	DEG.	0.3
Operating Temperature		erature	°C	0 ~ 70
Usable Fluid				Air
Reaction	ng re	at 1 MPa		0.23
Reaction Oberating Oberating Construction	at 0.5 MPa		0.15	
	Pr	at P MPa		$0.154 \times P + 0.07$
Weight g		BWA		42
		BWB		35

# Notes for Usage (BWA/BWB)

- 1. "Air Non-Leak" means that a single BWA unit has pressure maintaining ability for more than 24 hours (under constant temperature).
- 2. After installing parts of pressure maintaining circuit, confirm pressure maintaining by testing leakage at each connecting part using leak checker, etc. (Please install a pressure gauge in the circuit.)

- 5. Do not connect the coupler when contaminants are adhered on each end surface. (install a cover, or remove all contaminants with air blow before connection.) 6. Exceeding allowable offset leads to damage on internal parts. It is recommended to install a guide pin.
- This may also cause an air leak when disconnected under pressurization.
- 7. Even though this product is equipped with filter, please note that inadequate flushing may result in poor flow performance or malfunction due to clogging of the built-in filter.
- 8. When pressing to the connection limit, the force should be higher than reaction force and lower than 2.0kN.





This cannot be used in equipment that requires the leakage amount level that is confirmed by tracer gas leak testing using helium and hydrogen.

3. When maintaining pressure with BWA after disconnecting under pressurization, make sure it has a method and condition that it can connect with greater force than reaction force. (Even when using with Pallet Clamp, it is required to press with greater force than reaction force before locking action.) 4. Since the check valve of the supply side BWB is a metal seal, there may be a slight air leak when pressurized under disconnected state.



World's First



# Air Non-Leak Valve Air Double-Acting

model **BWQ** 

Pilot Check Valve with Air Non-Leak\* Function

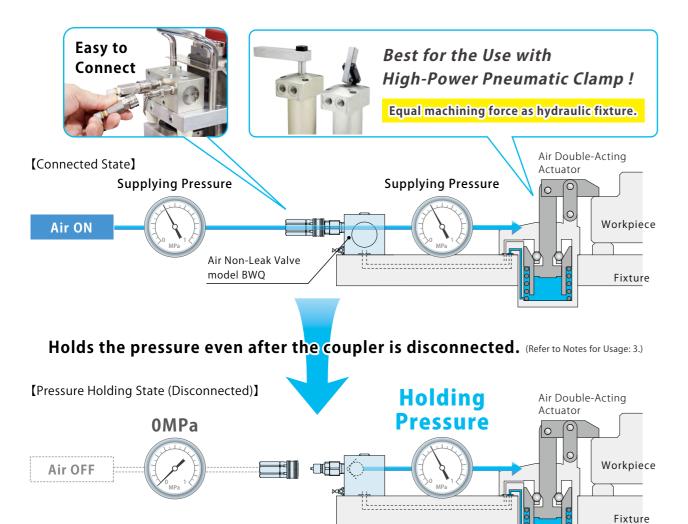
A2 port (outgoing lock air) maintains air pressure even after disconnected

from the air source unless air is provided to B1 port (release port).

\* "Air Non-Leak" means that the outgoing A2 port has pressure maintaining ability for more than 24 hours (under constant temperature).

Non-leak, which could only be achieved with hydraulics, is now possible with air.

# New release of the valve mode Bwo that achieves Air Non-Leak\*



# Setup Outside the Machine Improves Machine Up Time

Air non-leak function allows to disconnect a fixture from an air source and to prepare the fixture outside machine. This reduces machine down time and set up time.

# Reduce the Number of Circuits in the Machine

By holding the air pressure, the number of circuits for fixture inside the machine can be minimized.

 $\bigcirc$ 

# Outside Setup by Disconnecting Air of APC, Pallet Pooling, etc.

Because it is able to disconnect the fixture from the air source, it is suitable for pallet pooling. It allows to move pallets freely without concerns on handling of hoses, and it is also suitable for transferring with robot.

# • Energy-Saving with No Hydraulic Use

The non-leak function which could only be achieved with hydraulics is now possible with air.

Also, the same level of machining as a hydraulic fixture is possible by using with high-power pneumatic clamp.

Specifications	※ Refer to the catalog for detailed specification
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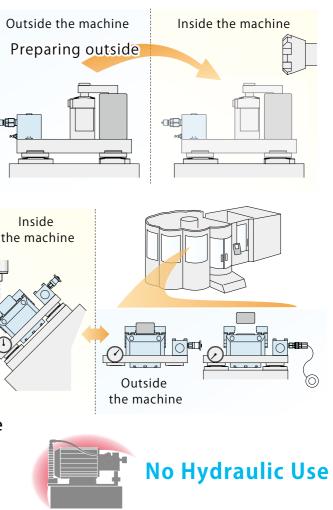
• Specifications »	nerei	to the catalog for detailed specificatio
Model No.		BWQ0100-□
Operating Pressure Range	MPa	0.2 ~ 1.0
Withstanding Pressure	MPa	1.5
Cracking Pressure	MPa	0.04
Pilot Pressure	MPa	Holding Pressure $\times$ 0.45 + 0.1 or mo
Min. Passage Area	mm <sup>2</sup>	8.8 (Coupler Part)
Operating Temperature	°C	0~70
Usable Fluid		Air
Applicable Coupler /		C0-1SF-SUS-FKM
Socket Model **1	kg	C0-13F-303-FMM
Weight		0.5

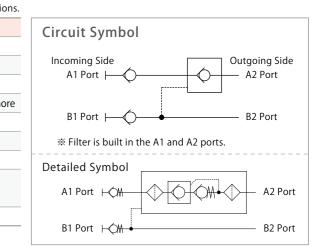
Note : %1. It shows the socket model number of compact coupler manufactured by NITTO KOHKI.

# Notes for Usage (BWQ)

- leak checker, etc. (Please install a pressure gauge in the circuit.)
- to maintain pressure with the check valve built in the body. (Control Valve Example: 5-port 3-position exhaust center)
- except during disconnecting/connecting operation.
- 5. Even though this product is equipped with filter, please note that inadequate flushing may result in poor flow performance or malfunction due to clogging of the built-in filter.







1. "Air Non-Leak" means that a single BWQ unit (A2 port) has pressure maintaining ability for more than 24 hours (under constant temperature). This cannot be used in equipment that requires the leakage amount level that is confirmed by tracer gas leak testing using helium and hydrogen. 2. After installing parts of pressure maintaining circuit, confirm pressure maintaining by testing leakage at each connecting part using

3. When disconnecting the socket of the coupler, make the socket on the both circuits to pressure zero and in an opened state in order 4. Before disconnecting/connecting the coupler, remove cutting chips and coolant with air blow, etc. Also, install the coupler cover



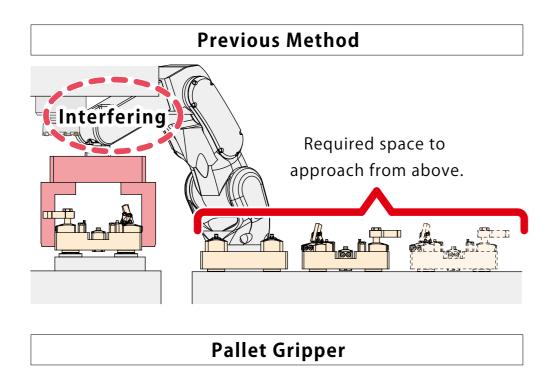
Master Cylinder

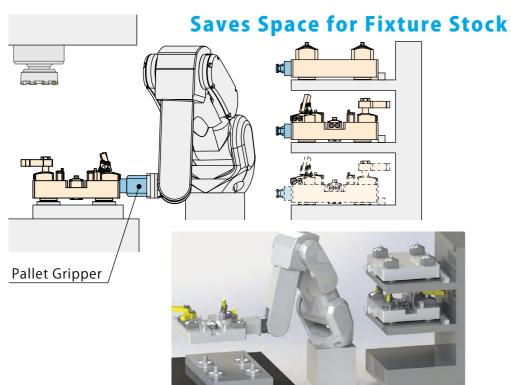
Tool Adapter

# Pallet Gripper

 $_{\rm model} \, WVA$ 

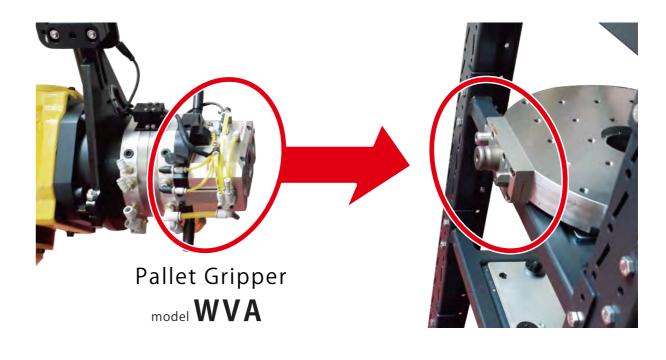
Moment-Resistible Pallet Gripper is suitable for pallet transfer. Side approaching enables to save space for fixture stock.



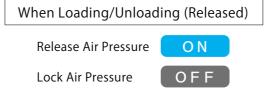


# Simplify Fixture Setup with Robot

# Side-Approaching Pallet Gripper



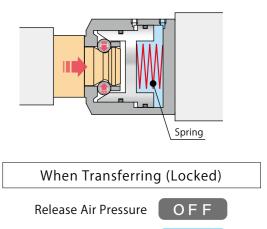
Pull Bolt Part Pallet Tool Adapter



Release action : The piston moves backward and the steel balls are set inside so that the tool adapter can be attached/detached.



**C**Action Description \* This is a simplified drawing. The actual part components may be different.



Lock Air Pressure

Lock action : The piston moves forward with lock air pressure and built-in spring, and pulls in the pull bolt of the tool adapter via the steel balls.

ΟN

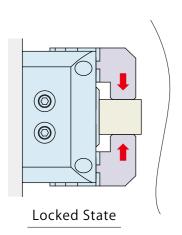
Self-locking function with spring prevents a workpiece fall even when air pressure drops to 0MPa in case of a power failure. X Usually it should be connected with spring force and lock air pressure.

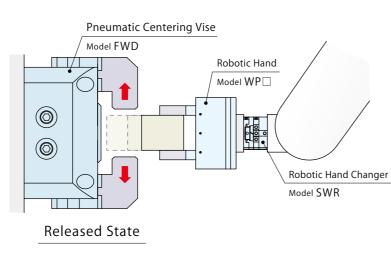


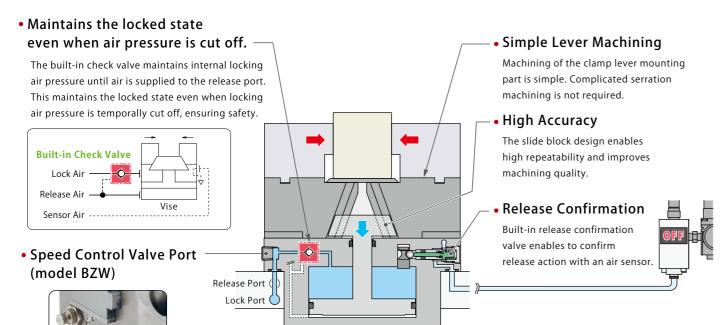
NEW Pneumatic Centering Vise [Built-in Check Valve] model **FWD** 

High Repeatability + High Cylinder Force + Safety Function to Maintain Locked State. Best for automation with powerful holding of workpiece by air pressure, and equipped with release action confirmation.

# High-Accuracy • High-Power Pneumatic Vise **Best for Automation with** Safety Function and Action Confirmation





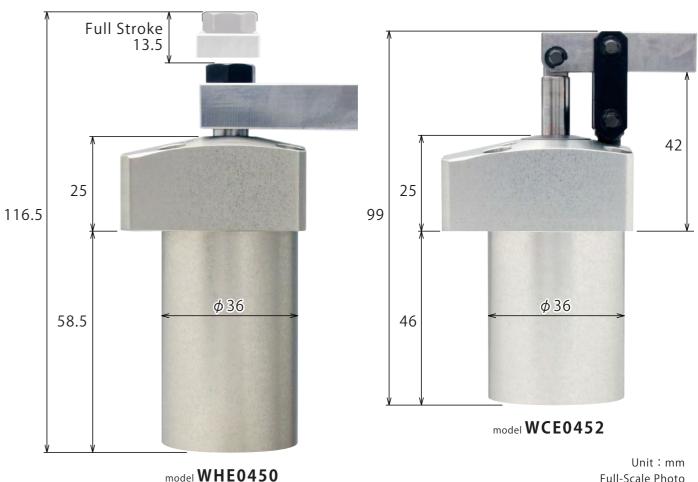




**High-Power Pneumatic Series 100,000** units of pneumatic fixture systems have been sold.

# Thanks to many requests, we have added

# long-awaited compact models to the lineup! **Enables Smaller Footprint • High Quality • Light Weight**





# NEW

# High-Power Pneumatic Swing / Link Clamp Compact Model model WHE0450/WCE0452

Exerts high clamping force powered by pneumatic and the most powerful holding force with mechanical lock among our products. Compact models are newly added to the lineup.



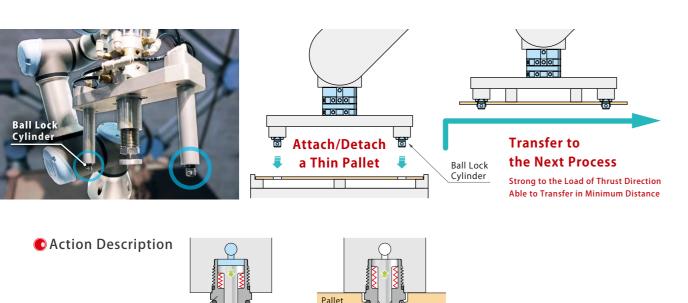
The description video of Ball Lock Cylinder

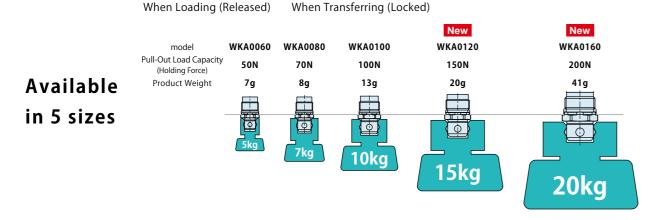




# Ball Lock Cylinder $_{\rm model} \, WKA$

The ball lock cylinder is used for transfer pallets, plates, temporary tool stocker, etc. 2 larger sizes have been added to the lineup.

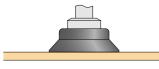




# **Suction Pad**

Ball Lock Cylinder

Limited Speed Low Suction Force



A small suction pad has critical weight limits due to low suction force. Also, it is weak to the moment in the side direction, so that transfer speed is limited. The suction force is affected by the roughness of the surface and is decreased due to deterioration and friction.

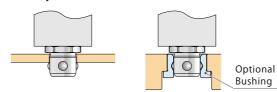
29

# **Ball Lock Cylinder**

(Ex.) Backlash Prevention with O-ring

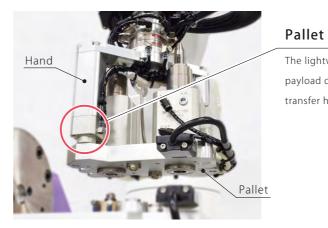
\* The O-ring is not included.

Powerful with Mechanical Lock, Light and Compact **Only 1 Circuit for Positive Pressure** 

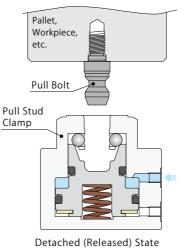


**Requires Machining of Mounting Hole** Machining of the hole can be simple by using the optional bushing.





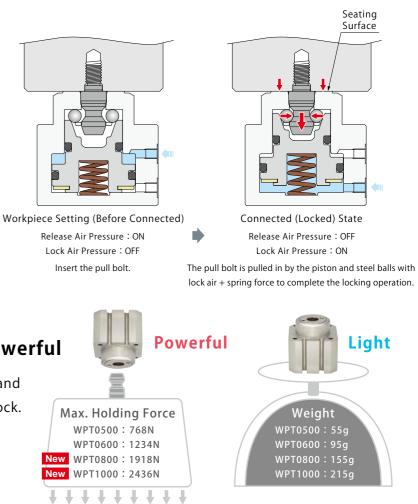
Action Description



Release Air Pressure : ON Lock Air Pressure : OFF Provide release air pressure, allowing for pulling in and out the pull bolt.

# Compact, Light, yet Powerful

Exerts powerful clamping force and holding force with mechanical lock.



The description video of High-Power Pull Stud Clamp is available on our website





# High-Power Pull Stud Clamp model WPT

Clamps by pulling the pull bolt. It can be used for many applications such as transferring and tool clamping. 2 larger sizes have been added to the lineup.

# Pallet Transfer with High-Power Pull Stud Clamp

The lightweight High-Power Pull Stud Clamp minimizes the reduction in payload capacity of the robot. Holding force is very powerful, and it can transfer heavy pallets, etc.



For FA • Industrial Robots







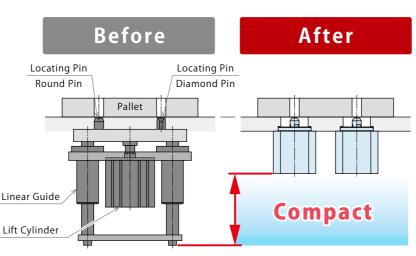
# Lifting Hole Clamp model SWJ

3 Functions in 1 Cylinder : Lift Cylinder, Locating Pin and Hole Clamp For locating of transfer equipment and saving space for lifting.



Load

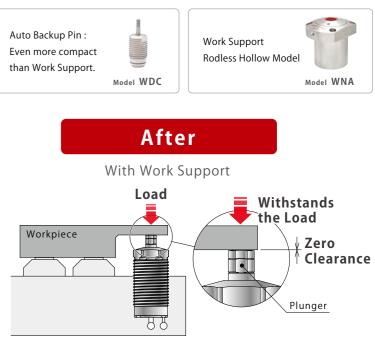




# Workpiece

Before

Without Work Support



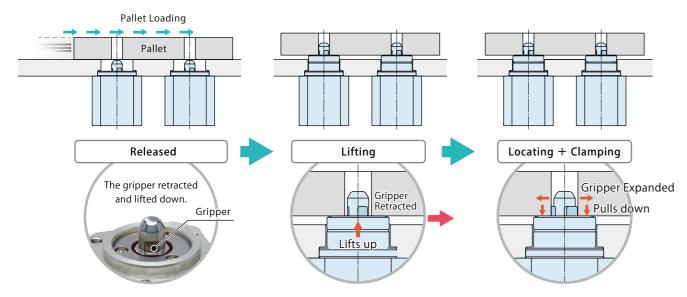
Chattering • Deformation

# The World's Smallest • Compact

Line-up of 7 Body Sizes (External Thread Part): M16, M22, M26, M30, M36, M45, M60 One of the world's smallest M16 size has been newly added to the lineup. For more compact equipment.

# **Excellent Machining Quality** with Multiple Work Supports

# Action Description



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# High-Power Pneumatic Work Support model WNC

Air sensing option : model WNC-M is added to the lineup.

# **Prevents Chattering • Deformation**

The plunger contacts with slight spring force. Wedge function locks the plunger firmly and holds it.

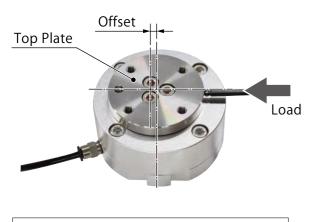




# **Compliance Module** model WRC

The floating top plate corrects misalignment of workpiece. Directly mounted to Kosmek Robotic Hand Changer model SWR.

# Misalignment of Workpiece is Corrected by the Floating Top Plate



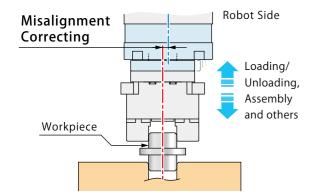
Air OFF **Floating State** 

The top plate can be floated when not supplying lock air pressure. When not receiving a load, the top plate returns to the center with the magnet.



ΟN Center Locking State Air

The top plate is centered and locked by supplying lock air pressure.



# Easy to Correct the Misalignment of Robot Transfer

Able to correct the misalignment between a robotic hand and a workpiece, or a hole and a part during transfer and assembly process with a robot. Program correction with a force sensor is not required. Mechanical floating function allows for easy setup.

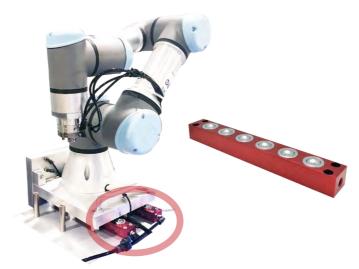






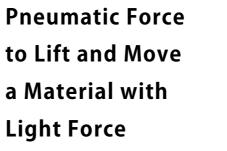
# Directly Mounted on Robotic Hand Changer

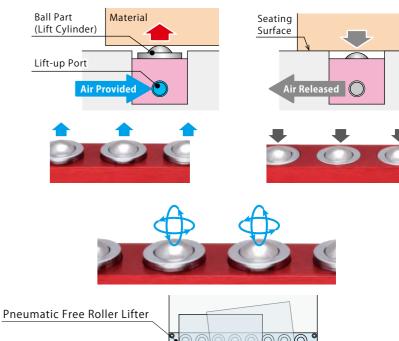
Compliance Module can be directly mounted on the tool adapter of model SWR (Payload 7kg ~ 25kg). Using with the Robotic Hand Changer enables to change highly flexible hands equipped with the Compliance Module and high-accuracy tools not equipped with the Compliance Module, allowing for various operations.



# LIFT UP

The ball part lifts up by providing air pressure to the lift-up port.







# The Balls Move 360° Flexibly

Able to move a heavy material easily to the locating point.



# 82 Options Available for Various Usage

Can be used for various methods such as transferring a workpiece, pallet, robot and others.



33



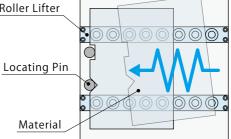
# Pneumatic Free Roller Lifter model **RQC**

Makes transfer and locating of heavy materials easy. The balls lift up with air pressure.

# AIR: ON

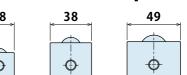
# LIFT DOWN AIR : OFF

The ball part lifts down with the material weight by releasing air pressure of the lift-up port.



(Application Example) Moving a material to the locating point.

# **Slot Width : 3 Options**



# Total Length : 150 ~ 1200mm